

# Avoiding Malfunctions Due To Software Failures by Automation of Software Production and Test

**Pannen wegen Software-Fehlern vermeiden durch Automatisierung von Software-Produktion und Test**

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## Facts and Issues

- Wirtschaftswoche summer / autumn 2002
  - increasing number of malfunctions in high-tech vehicles
  - major part by software malfunctions
- VDI-Nachrichten September 2002
  - Charles Simonyi, co-founder of Microsoft
    - „today we can design and control production of jumbo-jets, but programming still remains a handcrafted task“
- Trend in automotive industry: more software
  - e.g. 11. Aachener Kolloquium „Fahrzeug- und Motorenmechanik“
  - high quality software becomes a big challenge

## Looking on Car Mass Production

- well-defined production process
  - high productivity
  - high quality
  - pre-condition for quality assurance
  - saving company know-how
  - continuous process improvement
  
- automated software production becomes "the" issue
  - scalable approach needed to cover a broad range

## BSSE's Automation Approach ASaP

### ■ History

- 1992            ESA project on performance and FDIR validation (HRDMS)  
FDIR = Fault Identification and Recovery
- 1993            ESA project on behavioural validation (OMBSIM)
- 1995            ESA project on system fault tolerance (DDV)
- 1996            BSSE project on ATC protocol validation (OPAL)
- 1997            BSSE project on distributed fault-tolerant system (CADIS)  
turn-key system
- 1998            BSSE project on distributed critical control system (CRISYS)

### ■ ASaP milestones

- 1999 first version of fully automated environment (MSL / ISS)
- 2000 final delivery of automatically generated software package

## ASaP Improvements

### ■ State-Of-The-Art

- Productivity:                  1 man-hour      0.1 .. 10 LOC
- Bug Rate                         typical:             $10^{-2}$  / LOC  
                                       very good:       $10^{-3}$  / LOC

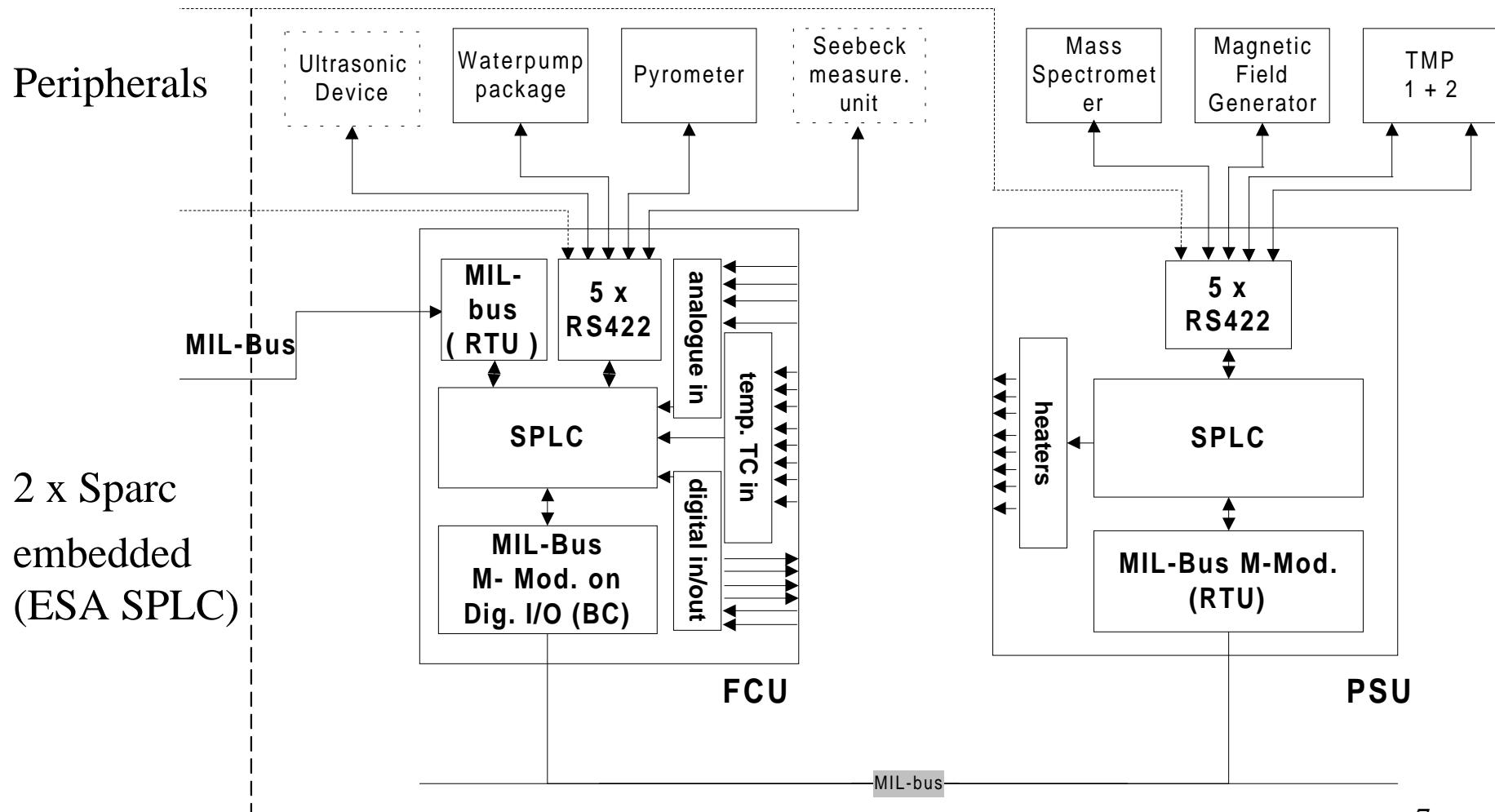
N.E.Fenton, 2000

### ■ Automated Software Production and Test (ASaP)

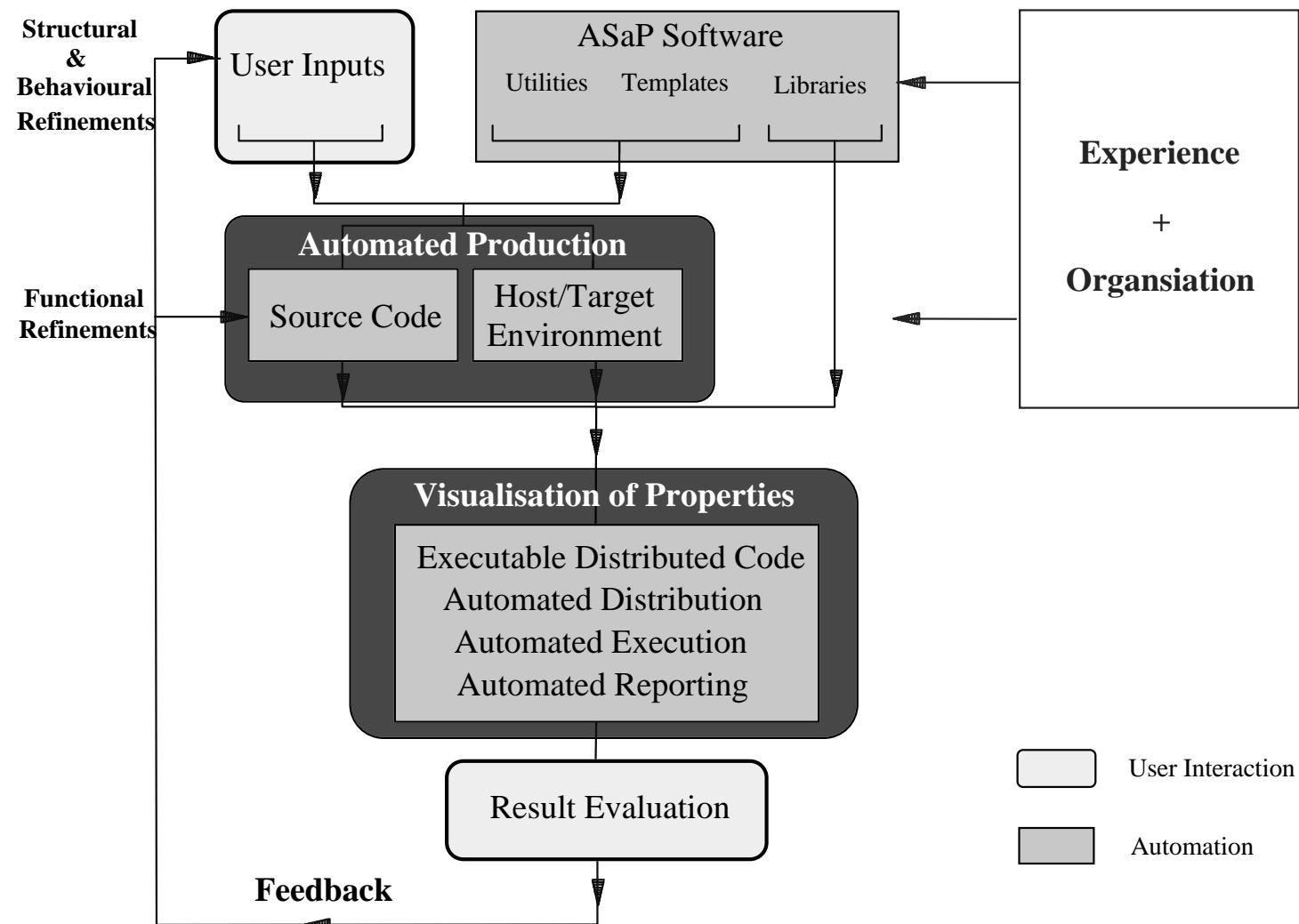
- Productivity                    1 PC-hour        16,000 .. 320,000 LOC  
                                      1 .. 20 man-years (my)  
                                      1600 mh/my    10 LOC / mh
- Bug Rate                         $\approx 0 .. 10^{-5}$  / LOC      5

**Quality is not expensive  
if a new technology is applied**

## Example: Distributed Real-Time System (MSL / ISS)



# Incremental Generic Development Cycle of ASaP



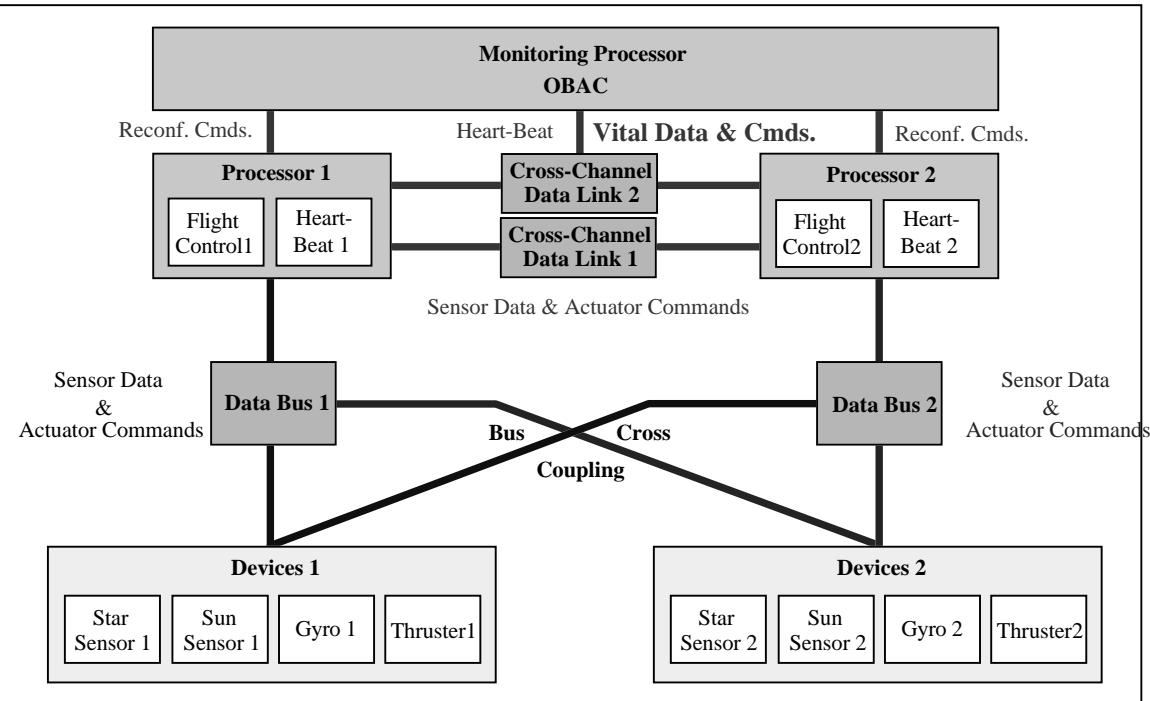
## Benefits by ASaP

- flexibility for changes and refinements
  - generic approach
  - compact user inputs
- shorter development cycle
  - short generation time
  - incremental refinements
- higher dependability
  - fault prevention by intensive checks of user inputs
  - fault identification by built-in assertions and visualisation
  - fault tolerance by coverage of exceptions, built-in mechanisms
- higher usability
  - fast feedback from real system
  - little effort to optimise the user interface

## Potential Application Areas in Automotive Industry

- Vehicle
  - system management
  - subsystem / unit software
- User Interface / Infotainment
  - user operation
  - unit management
  - unit software
- Vehicle Manufacturing
  - automated verification of manually coded robot programs vs. CAD
  - automated generation of robot programs from CAD data
- Project and Contractor Management
  - integration of COTS and sub-contractor software
  - quality checks and evaluation of software

# Fault-Tolerant Systems and Risks



**ESA Project DDV**  
 validation of the  
 exception handling  
 of a fault-tolerant system

## Sporadic System Failure

- computer C1 fails
- computer C2 takes over control
- C1 issues an actuator command before it fails
- C2 does not get this information
- C2 issues the same command
- !! the system fails !!

## Risk Reduction by Automation

- Can such problems be identified in advance?
- Answer by automated software production: YES
  - framework implies problem classification
  - less time needed for implementation,  
more time available for system engineering
  - better visualisation of properties

# Inputs in User Notation and Derived Output (MSL Database)

| Name of Signal | Data Type | Input Range | Physical Range    | Acqui. Rate | HW Module | Calibration Type |
|----------------|-----------|-------------|-------------------|-------------|-----------|------------------|
| CFDdrive_pot   | REAL32    | 0 - 10V     | 0 - 200 mm        | 100         | ASM F1    | FctASM1_Std      |
| CFDrot_pot1    | REAL32    | 0 - 10V     | 0 - 360 °         | 100         | ASM F1    | FctASM1_Std      |
| CFDrot_pot2    | REAL32    | 0 - 10V     | 0 - 360 °         | 100         | ASM F1    | FctASM1_Std      |
| CF_reg_v_pot   | REAL32    | 0 - 10V     | 0 - 270 °         | 10          | ASM F1    | FctASM1_Std      |
| GS_press_low   | REAL32    | 0 - 10 V    | 0 - 2 bar abs.    | 10          | ASM F1    | FctASM1_Std      |
| CFVpenn_chamb  | REAL32    | 0 - 10 V    | 1.e-7 - 1000 mbar | 1           | ASM F1    | FctASM1_Pressure |
| VGSpenning_ms  | REAL32    | 0 - 10 V    | 1.e-7 - 1000 mbar | 1           | ASM F1    | FctASM1_Pressure |

```

T_database_entry MSL_db_desc[ ]={

    /* address in DB */          (int*)&MSL_db.LRT_HK_A1.CFDdrive_pot,
    /* offset in DB */           (int)CFDdrive_potDBoff,
    /* #samples */                100,
    /* size of data type */      sizeof(REAL32),
    /* id of type */             7,
    /* copy DB data */           0,
    /* calibration function */  {(int*)FctASM1_Std_CFDdrive_pot,
    /* supervision structure */   {
        /* SV function */          (int*)&limChckREAL32,
        /* limit definitions */    CFDdrive_pot_suarr,
    }
    },
    /* post-processing function */ {(int*)NULL}
},

```

## More Derived Files (Subset Only)

```

REAL32 FctASM1_Std_CFDdrive_pot(UINT16 Data)
{
    REAL32 buffer;
    INT32 value;

    /* ADC correction (including amplifier correction) */
    buffer = (Data - ADCCorrASM1[0][0].Offset) * ADCCorrASM1[0][0].Gain;

    /* conversion to physical units */
    value = (REAL32) ((REAL32)0) + ((REAL32) 200 - (REAL32) ((REAL32)0)) /
            ( (REAL32) ((1<<12) - 1) ) * buffer;
    return value;
}
  
```

```

#include "frametypesDB.h"

/* MSL database */
TyDatabase MSL_db;

/* Recording of database updates */
int updateDBCnt=0;
int DBupdate[TOT_DATABASE_ITEMS];

/* # of instances of telemetry frames */
#define TM_BUFF_INST 2
  
```

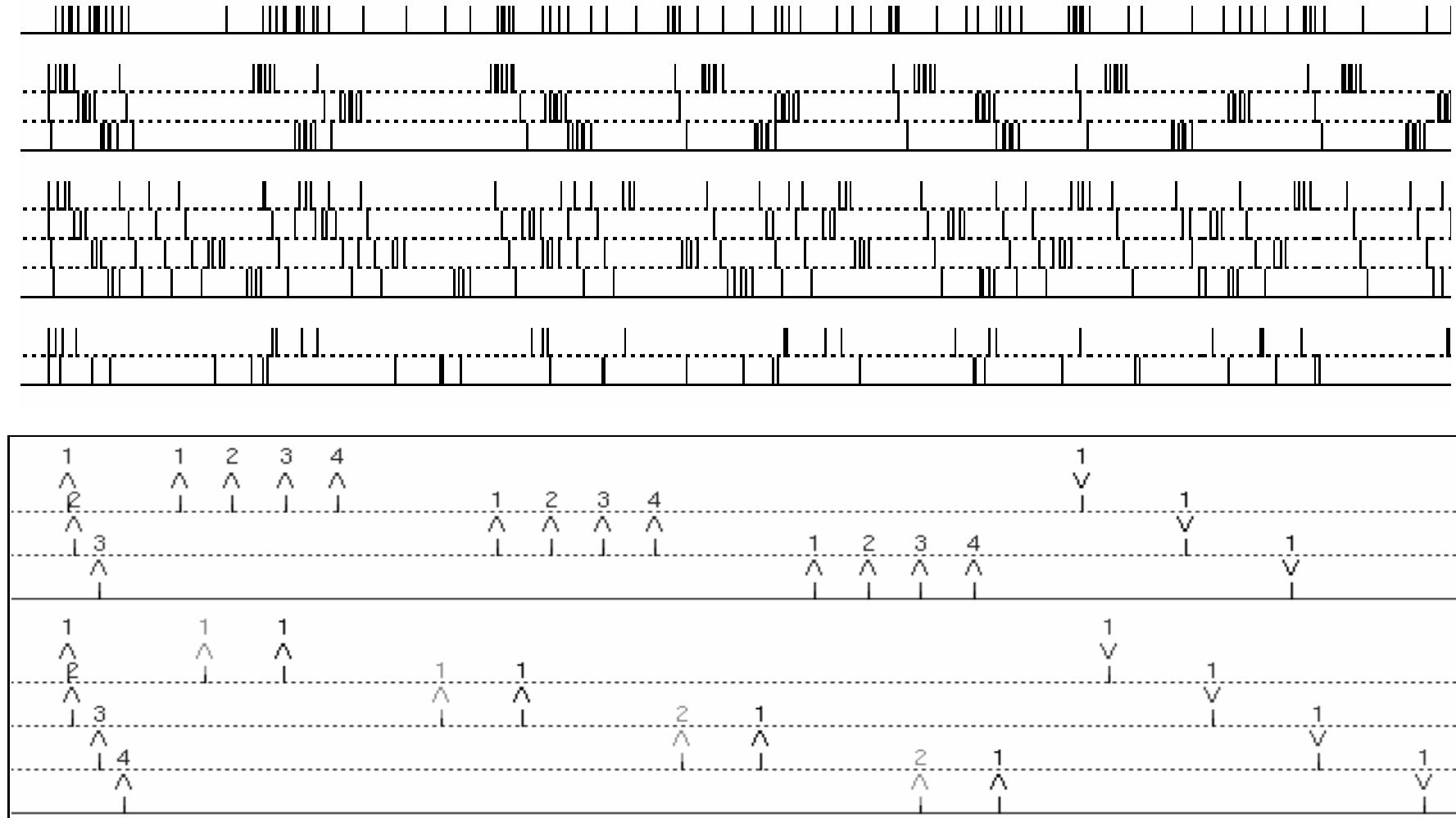
```

int LRT_HS_framePtr=0;
int LRT_HS_frameInd=0;
TyTMbuffer_LRT_HS LRT_HSArr[TM_BUFF_INST];

/* Array pointing to TM frame instances */
TyTMbufferArr TMbufferArr []=
{
    {LRT_HK_A1_ID,      (int*)&LRT_HK_A1Arr},
    {LRT_HK_D1_ID,      (int*)&LRT_HK_D1Arr},
    {LRT_HK_D2_ID,      (int*)&LRT_HK_D2Arr},
    {LRT_HS_ID,         (int*)&LRT_HSArr}
};

#define TM_BUFFER_ARR_SIZE
        sizeof(TMbufferArr)/sizeof(TyTMbufferArr)
  
```

# Visualisation of Properties: Timing and Communication



Reports available after 15 minutes starting by delivery of user's spreadsheet inputs<sup>15</sup>

## Achievements

- distributed real-time system
  - within 30 minutes equivalent of about 5 man-years (my)
  - 80,000 LOC (environment: 200,000 LOC)
- distributed, synchronised database
  - within 30 minutes equivalent of about 1 my
  - 16,000 LOC and more
- operations on data types, interfaces etc.
  - within 1 minute equivalent of about 2 my

## We give warranty!

**"accepted user inputs are  
automatically transformed into  
correct and immediately executable software  
when applying an automated production process  
established by us"**

## How and Where Can ASaP be Applied?

- Use of existing products
  - distributed critical real-time and control systems
  - data processing, distributed databases, GUIs
  - test case generation
  - integration and subcontractor management
  - user support possible
- Customised ASaP approach
  - know-how transfer
  - definition of an appropriate approach
  - building of the needed environment

# Customising ASaP



- Analysis of current manual procedures
  - similar to „REFA“ in case of hardware
  - identification of the most generic approach  
maximum coverage of application area
- Definition of the user interface
  - identification of driving parameters  
minimum set of user inputs
  - re-use of current environment (if any)  
building of an interface to the user's world
- continuous optimisation of ASaP procedures
  - provision of analysis tools
  - continuous benchmarking to check productivity and quality
  - continuous process improvement

This was a very short introduction, but ...  
we are available today

- for further discussions
- to show more details
- to give a demo on

„Instantaneous System and Software Generation“ (ISG)

**15 minutes from user's spreadsheet inputs to reports**

- 10 minutes generation time
- 3 minutes system execution
- 2 minutes report generation